

* Dimensions: * Seven base quantities referred as
Seven dimensions of physical world.

* Represented by using square brackets.

Base quantity	Dimensional formula
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1. Mass	$[M]$
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2. length	$[L]$
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3. time	$[T]$
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4. current	$[A]$ or $[I]$
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5. Temperature	$[K]$ or $[\theta]$
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6. Luminous intensity	$[cd]$
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7. Amount of Substance	$[mol]$
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Definition: The powers to which the base quantities are raised to represent the quantity are called dimensions of that quantity.

Ex: Speed : $\frac{\text{distance}}{\text{time}} \Rightarrow v = \frac{d}{t}$

Dimensions of speed in mass $\rightarrow 0$

length $\rightarrow 1$
time $\rightarrow -1$ $[v] = [M^0 L^1 T^{-1}]$

$$[v] = \frac{[d]}{[t]} = \frac{[L]}{[T]} = [L T^{-1}]$$

Dimensions of speed $\rightarrow 0, 1, -1$

Dimensional formula $\rightarrow [M^0 L^1 T^{-1}]$
of speed

Dimensional equation $\rightarrow [v] = [M^0 L^1 T^{-1}]$
of speed

Notes:

* 1. [Speed] = [Velocity] = $[L T^{-1}]$

* Area = length \times

2. [Distance] = [Displacement] = $[L]$

breadth

3. Momentum $P = \text{mass} \times \text{velocity}$

$[A] = L^2$

$P = m v$

* Volume = length \times

$[P] = [m] [v]$

breadth \times

$[P] = [M L T^{-1}]$

height

4. acceleration $a = \frac{\text{change in velocity}}{\text{time}}$

$[v] = L^3$

$[a] = \frac{[v]}{[t]}$

$= \frac{[M]}{[L^3]}$

$= \left[\frac{L T^{-1}}{T} \right]$

$= [M L^{-3}]$

$= [L T^{-2}]$

5. Force $F = \text{mass} \times \text{acceleration}$

$[F] = [m] [a]$

$= [M L T^{-2}]$

6. Impulse $J = \text{change in momentum}$ (or) Force \times time

$$\begin{aligned}[J] &= [P] & P &\rightarrow \text{momentum} \\ &= [m v] & m &\rightarrow \text{mass} \\ &= [M L T^{-1}] & v &\rightarrow \text{velocity}\end{aligned}$$

$$[\text{impulse}] = [\text{momentum}] = [M L T^{-1}]$$

7. Workdone $W = \text{Force} \times \text{displacement}$

$$\begin{aligned}[W] &= [F] [S] & F &\rightarrow \text{Force} \\ &= [M L T^{-2}] [L] & S &\rightarrow \text{displacement} \\ &= [M L^2 T^{-2}]\end{aligned}$$

$$[\text{Energy}] = [K.E] = \left[\frac{1}{2} m v^2 \right] \quad K.E = \text{kinetic energy}$$

$$\begin{aligned}(\text{or}) \quad [P.E] &= [m] [v]^2 & P.E = \text{potential energy} \\ &= [M] [L T^{-1}]^2 & m \rightarrow \text{mass} \\ &= [M L^2 T^{-2}] & v \rightarrow \text{speed}\end{aligned}$$

Torque $\tau = \text{Force} \times \text{per distance}$

$$\begin{aligned}[\tau] &= [F] \times [r] \\ &= [M L T^{-2}] [L] \\ &= [M L^2 T^{-2}]\end{aligned}$$

$$\therefore [\text{Workdone}] = [\text{Energy}] = [\text{Torque}] = [ML^2 T^{-2}]$$

8. power $P = \frac{\text{Work}}{\text{time}}$

$$\begin{aligned} [P] &= \frac{[W]}{[t]} \\ &= \frac{[ML^2 T^{-2}]}{[T]} \\ &= [ML^2 T^{-3}] \end{aligned}$$

9. Intensity $I = \frac{\text{Energy}}{\text{Area} \times \text{time}}$
(or)

Solar constant

$$\begin{aligned} [I] &= \frac{[E]}{[A][t]} \\ &= \frac{ML^2 T^{-2}}{[L^2][T]} \\ &= [MT^{-3}] \end{aligned}$$

10. pressure $P = \frac{\text{Force}}{\text{Area}}$
(or)

stress $[P] = \frac{[F]}{[A]}$

Some formulae for elastic modulus $[E] = [ML^{-1} T^{-2}]$ $E = \frac{\text{Stress}}{\text{Strain}}$	$\left. \begin{aligned} &= \frac{[ML^{-2}]}{[L^2]} \\ &= [ML^{-1} T^{-2}] \end{aligned} \right]$
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$$\begin{aligned} *11. \text{Strain} &= \frac{\text{change in length (or) Area (or) Volume}}{\text{initial length (or) Area (or) Volume}} \\ &= \frac{\Delta L}{L} \text{ (or)} \frac{\Delta A}{A} \text{ (or)} \frac{\Delta V}{V} \\ \therefore [\text{Strain}] &= [M^0 L^0 T^0] \end{aligned}$$

$$*12. \text{Coefficient of elasticity } E = \frac{\text{Stress}}{\text{Strain}}$$

(or)
Elastic modulus

$$[E] = \frac{[\text{Stress}]}{[\text{Strain}]}$$

$$[E] = \frac{[M L^{-2} T^{-2}]}{[M^0 L^0 T^0]}$$

$$[E] = [M L^{-1} T^{-2}]$$

$$\therefore [\text{pressure}] = [\text{stress}] = [\text{Elastic modulus}]$$

$$= [M L^{-1} T^{-2}]$$

$$13. \text{Energy density} = \frac{\text{Energy}}{\text{Volume}}$$

$$[U] = \frac{[E]}{[V]} = \frac{[M L^2 T^{-2}]}{[L^3]} = [M L^{-1} T^{-2}]$$

$$\text{Energy density of electric field } U_E = \frac{1}{2} \epsilon_0 E^2 \quad \begin{array}{l} [E \rightarrow \text{electric field}] \\ [\epsilon_0 \rightarrow \text{permittivity of free space}] \end{array}$$

$$\text{Energy density of magnetic field } U_B = \frac{B^2}{2\mu_0}$$

$B \rightarrow \text{magnetic field}$

$\mu_0 \rightarrow \text{permability}$

$$\therefore [\text{Energy density } U] = [U_E] = [U_B] = [M L^{-1} T^{-2}]$$

$$14. \text{ coefficient of viscosity} = \frac{\text{Force} \times \text{distance}}{\text{Area} \times \text{velocity}}$$

$$\begin{aligned} [\eta] &= \left[\frac{F d}{A v} \right] \\ &= \left[\frac{M L T^{-2} L}{L^2 L T^{-1}} \right] \\ &= \left[\frac{M L^2 T^{-2}}{L^3 T^{-1}} \right] \end{aligned}$$

$$15. \text{ Surface tension: } [T] = [M L^{-1} T^{-1}]$$

$$\left[\frac{\text{Force}}{\text{length}} \right]$$

$$\left[\frac{F}{L} \right]$$

$$\left[\frac{M L T^{-2}}{L} \right]$$

$$\left[M T^{-2} \right]$$

16. velocity gradient = $\frac{\text{velocity}}{\text{distance}}$ pressure gradient =
(or)

$$\text{frequency } \mathfrak{f} = \frac{[V]}{[L]} = \frac{[L\bar{T}']}{[L]} = [T^{-1}]$$
$$= \frac{[M L^{-1} T^{-2}]}{[L]} = [M L^{-2} T^{-2}]$$

$$[\text{velocity gradient}] = [\text{frequency}] = [T^{-1}]$$

17. * Angle plane angle = $\frac{\text{arc length}}{\text{radius}}$

$$[\text{plane angle}] = [M^0 L^0 T^0]$$

Solid angle = $\frac{\text{surface area}}{\text{square of radius}}$

$$[\text{solid angle}] = [M^0 L^0 T^0]$$

$$[\text{Angle}], [\text{plane angle}], [\text{solid angle}] = [M^0 L^0 T^0]$$

18. Angular velocity $\omega = \frac{\text{Angle}}{\text{time}}$

$$[\omega] = \left[\frac{M^0 L^0 T^0}{T} \right]$$

$$[\omega] = [T^{-1}]$$

$\therefore [\omega] = [\text{frequency}] = [\text{velocity gradient}] = [T^{-1}]$

19. Angular acceleration $\alpha = \frac{\text{Angular velocity}}{\text{time}}$

$$[\alpha] = \frac{[\omega]}{[t]} = \frac{[T^{-1}]}{[T]} = [T^{-2}]$$

20. Angular momentum $L = \text{mass} \times \text{velocity} \times \text{radius}$

(Same for

$$[L] = [mv\tau]$$

plank's constant)

$$= [M L T' L]$$

$$= [M L^2 T']$$

* Speed of light $c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/s}$

$$[c] = \left[\frac{1}{\sqrt{\mu_0 \epsilon_0}} \right] \text{(or)} \left[\frac{1}{\mu_0 \epsilon_0} \right]^{\frac{1}{2}} \text{(or)} [\mu_0 \epsilon_0]^{-\frac{1}{2}} = [L T^{-1}]$$

* plank's constant $h = \frac{\text{Energy}}{\text{frequency}}$

$$[h] = \left[\frac{E}{\nu} \right]$$

$$[h] = \left[\frac{M L^2 T^{-2}}{T^{-1}} \right]$$

$$[h] = [M L^2 T^{-1}]$$

* universal gravitational constants $G_1 = \frac{F r^2}{m_1 m_2}$

$$[G_1] = \left[\frac{M L T^{-2} L^2}{M^2} \right]$$

$$[G_1] = [M^{-1} L^3 T^{-2}]$$

* $F = \frac{1}{4\pi\epsilon_0} \frac{c^2}{r^2} \Rightarrow \frac{c^2}{4\pi\epsilon_0} = F r^2$

$$\begin{aligned} \left[\frac{c^2}{4\pi\epsilon_0} \right] &= [F r^2] \\ &= [M L T^{-2} L^2] \\ &= [M L^3 T^{-2}] \end{aligned}$$

* Universal gas constant $R = \frac{PV}{nT}$

$$[R] = \left[\frac{M L^2 T^{-2} L^3}{mol K} \right]$$

$$= [M L^2 T^{-2} mol^{-1} K^{-1}]$$

* Boltzmann's constant $K = \frac{\text{Energy}}{\text{temperature}}$

$$= \left[\frac{M L^2 T^{-2}}{K} \right]$$

$$= [M L^2 T^{-2} K^{-1}]$$

Dimensionless quantities: plane angle, solid angle, T-ratios ($\sin\theta, \cos\theta, \tan\theta \dots$), Relative density, Strain, refractive index ($\mu = \frac{c}{v}$), pure numbers, Trigonometric, logarithmic, exponential functions

Ex: $y = A \sin(\omega t)$ $y \rightarrow \text{distance}$

$$[\omega t] = [M^0 L^0 T^0] \quad t \rightarrow \text{time}$$

$$y = A e^{(ct)}, \quad y = A \log(\omega t)$$

$$[ct] = [M^0 L^0 T^0] \quad [\omega t] = [M^0 L^0 T^0]$$

principle of homogeneity:

* Any two physical quantities which are going to be added, subtracted or equated must have same dimensions.

Ex: (i) $a + b \rightarrow$ valid * All terms in a

$$[a] = [b] \quad \text{given equation}$$

should have

(ii) $c - d \rightarrow$ valid same dimensions.

$$[c] = [d]$$

(iii) $P = Q \rightarrow$ valid

$$[P] = [Q]$$

(iv) $ax + by = cp + dq \rightarrow$ valid

For L.H.S $[ax] = [by] = [cp] = [dq]$ R.H.S

Ex: $y = At + Bt^2$ $y \rightarrow$ distance

$t \rightarrow$ time

$$[y] = [At] = [Bt^2]$$

$$[y] = [At]$$

$$[y] = [Bt^2]$$

$$[A] = \frac{[y]}{[t]} = \frac{[L]}{[T]}$$

$$= [L T^{-1}]$$

$$[B] = \frac{[y]}{[t^2]} = \frac{[L]}{[T^2]}$$

$$= [L T^{-2}]$$

Ex: (i) $y = A \sin(\omega t)$ $y \rightarrow \text{distance}$

$t \rightarrow \text{time}$

What is $[A] = ?$ $[\omega] = ?$

Trigonometric functions are dimensionless

$$[\omega t] = [M^0 L^0 T^0]$$

$$[\omega] = \frac{[M^0 L^0 T^0]}{T}$$

$$[\omega] = [T^{-1}] \checkmark$$

and $[y] = [A]$

$$\therefore [L] = [A] \checkmark$$

(ii) $y = A \log(Bx + ct)$ $x, y - \text{distance}$

$t - \text{time}$

$$[A] = [y] \Rightarrow [Bx + ct] = [M^0 L^0 T^0] [A] = ? [B] = ? [C] = ?$$

$$= [L]$$

$$[Bx] = [M^0 L^0 T^0] \quad [ct] = [M^0 L^0 T^0]$$

$$[Bx] = [1] \quad [ct] = [1]$$

$$[B] = \left[\frac{1}{x} \right] \quad [C] = \left[\frac{1}{t} \right]$$

$$= \left[\frac{1}{L} \right] \quad [C] = \left[\frac{1}{T} \right]$$

$$= [L^{-1}] \quad [C] = [T^{-1}]$$

$$(iii) \quad y = A e^{(Bt)}$$

$y \rightarrow \text{distance}$

$t \rightarrow \text{time}$

$$[A] = ? \quad [B] = ?$$

\therefore exponential functions are dimension less

$$[Bt] = [M^0 L^0 T^0]$$

$$[Bt] = [1]$$

$$[B] = \left[\frac{1}{t} \right]$$

$$= \left[\frac{1}{T} \right]$$

$$= [T^{-1}]$$

$$[B] = [T^{-1}]$$

$$[B] = [T^{-1}]$$

$$[T]$$

$$[T^2] = [T \cdot T]$$

$$[T^2]$$

$$[T^2] = [L^2] \quad \text{and} \quad [L^2]$$

Dimensionless quantities can't have dimensions

Applications:

1. Checking the dimensional consistency of equations: We can check any equation

Ex: whether it is dimensionally correct equation or not.

Ex: We know that

the second equation of motion

$$S = ut + \frac{1}{2}at^2 \quad S \rightarrow \text{displacement}$$

According to principle of $\cup \rightarrow \text{initial speed}$
homogeneity $a \rightarrow \text{acceleration}$

$$[L \cdot H \cdot S] = [R \cdot H \cdot S] \quad t \rightarrow \text{time.}$$

Let us check it

$$[S] = [L]$$

$$[ut] = [L T^{-1} T]$$

$$= [L]$$

$$[at^2] = [L T^{-2} T^2]$$

$$= [L]$$

$$\therefore [S] = [ut] = [at^2]$$

$\therefore S = ut + \frac{1}{2}at^2$ is dimensionally correct.

We know that it is mathematically correct also.

$$\text{If } S = ut + \frac{1}{2} at^2$$

we know that it is wrong mathematically
(or)
physically

Let me check the dimensionality

$[L \cdot H \cdot S] = [R \cdot H \cdot S]$ is valid or not

$$[S] = [L]$$

$$[ut] = [L T^{-1} T] = [L]$$

$$[at^2] = [L T^{-2} T^2] = [L]$$

* $S = ut + \frac{1}{2} at^2$ equation is dimensionally correct

but mathematically wrong.
(or)
physically

Important note: * A dimensionally correct equation
need not to be correct mathematically

but

* A mathematically correct equation
must be dimensionally correct.

2. Deducing relation among various physical quantities:

Ex: A body is dropped from a height 'h',
the time taken to reach ground is 't'

Q. Express dimensional formula of time "t"
in terms of height "h", acceleration due to
gravity "g"

$$t \propto h^x g^y$$

$$t = K h^x g^y$$

According to principle of homogeneity.

$$[t] = [h^x g^y]$$

$$[t] = [h]^x [g]^y$$

$$[T] = [L]^x [L T^{-2}]^y$$

$$[M^0 L^0 T^1] = [L^x] [L^y T^{-2y}]$$

$$[M^0 L^0 T^1] = [L^{x+y} T^{-2y}]$$

$$x+y=0, -2y=1$$

$$\begin{aligned} x &= -y & y &= -\frac{1}{2} \\ &= -(-\frac{1}{2}) & &= \frac{1}{2} \end{aligned}$$

$$\therefore t = K h^{1/2} g^{-1/2}$$

$$t = K \sqrt{h} \frac{1}{\sqrt{g}}$$

$$\therefore t = K \sqrt{\frac{h}{g}}$$

mathematically $K = \sqrt{2}$ (experimentally found value).

Q. Express base quantities in terms of derived quantities:

Ex: Distance travelled by the body depends on Force F, velocity v, time t

express dimensional formula of distance (in length) in terms of F, v, t.

$$\therefore L \propto F^x v^y t^z$$

$$[L] \propto [F]^x [v]^y [t]^z$$

$$[L] \propto [M L T^{-2}]^x [L T^{-1}]^y [T]^z$$